

Designing network architecture from differential equation view

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Abstract

Deep neural networks are powerful models used in many computer vision and natural language processing applications. By designing better network architecture, we can achieve better performance on given task. In this paper, we connect network design with numerical ordinary differential equations. By simulating a popular numerical differential equations algorithm, Adams, we propose a new architecture and test its performance on CIFAR-10 dataset.

1 Introduction

Deep neural networks are state of the art models in many aspects, including computer vision and natural language processing. However, training deep networks is a difficult and expensive task. To address this problem, many network structures are proposed to make training easier and improve generalization of model. One of those models is Resnet proposed by He et al. [1]. They introduce skip connection between layers to avoid gradient vanishing, allowing training of deeper network. Resnet is very effective and show great performance in different computer vision tasks.

However, it is still a tough task to understand why skip connection helps training in Resnet. A lot of work has been done trying to explain it. E. [4] proposed a possible explanation by connecting neural networks with dynamical systems. He suggests that each module in Resnet can be regarded as one step on Euler discretization in solving differential equation. That is,

$$y_{n+1} = y_n + f(y_n, \theta_n).$$

This observation inspired many attempts to combine network design and numerical ordinary differential equation algorithms. Lu et al. [5] suggests that many network, such as Densenet [3], Polynet [11], can be viewed as different numerical discretization of differential equations. [5] combines neural networks with linear multistep method and proposed LM-Resnet.

In this paper, we construct a network simulating the famous numerical ODE algorithm, Adams. We experiment it on CIFAR-10 dataset and compared its performance between fixed coefficients between layers and learnable coefficients.

2 Related works

Following the idea that recognizing Resnet module as one step in Euler discretization, Lu et al. [5] suggest that many variants of Resnet can be viewed as different numerical scheme of ODE. They proposed LMnet, designing network by following formula:

$$y_{n+1} = (1 - k_n)y_n + k_n y_{n-1} + f(y_n, \theta_n).$$

Later, more attempts are made to design network architecture using ODE numerical method. Zhu et al. [6] suggest that Runge-Kutta method can be utilized in network designing. Runge-Kutta method is a famous numerical method in ODE solving. Generally, it can be written as [7]:

$$y_{n+1} = y_n + h \sum_{i=1}^s b_i z_i$$

in which

$$z_i = f(t_n + c_i h, y_n + g \sum_{j=1}^s a_{ij} z_j).$$

3 Adams and Adamnet

In this paper, we design an architecture following Adams algorithm and making experiments with it. Adams is a famous numerical ODE algorithm. Generally, its numerical scheme can be written as following formula:

$$y_{n+1} = y_n + \sum_{s=1}^k \beta_s f(y_{n-s}, t_{n-s}),$$

where k is a positive integer. Algorithm following this formula is called k -step explicit Adams method. To construct a similar architecture in neural network, we use

$$y_{n+1} = y_n + \sum_{s=1}^k \beta_s f(\theta_{n-s}, y_{n-s})$$

where y_i is the output of i th layer, f_i represents the i th Resnet module [2], which can be written briefly as BatchNormalization(BN) [8]-relu-conv-BN-relu-conv. Other parts are the same as Resnet [1]

4 Experiment and results

We test two kinds of model: $k=2$ and $k=3$ on CIFAR-10 dataset with data augmentation in [9]. The network structure is mainly the same as pre-activate Resnet [2] except adding extra skip connections according to Adams method. Our training strategy is similar with [5]: Training by SGD with momentum of 0.9 and weight decay of 0.0001. Batch size is 128. The whole training takes 160 epochs. Learning rate is initialized 0.1 and divided by 10 at epoch 80 and 120. Different with [5], when choosing β_i , we take two different strategies:

- (A) Set β_i as trainable parameters and initialize it by random number sampling from $\beta_1 : U(1, 1.1) (k=2)$ and $\beta_1 : U(1, 1.1) \beta_2 : U(-1, -0.9) (k=3)$
- (B) Fix β_i as constant given by Adams method: $\beta_1 = 1.5 (k=2)$ and $\beta_1 = 23/12, \beta_2 = -4/3 (k=3)$

We compare the results on CIFAR-10 with Resnet [1] and LMResnet [5] in Table 1. (A) stands for using learnable β_i and (B) stands for fixed β_i .

5 Conclusion and Discussion

In this paper, we design a network called Adamnet according to Adams method and compare its performance with Resnet [1] and LM-Resnet [5] on CIFAR-10 dataset. From the results on Table-1, we can see that Adamnet performs slightly better when the network is shallow and slightly worse when the network is deep. We also observe an interesting phenomenon: fixed β_i usually makes the result slightly worse than trainable ones, which is consistent with our intuition because it has less trainable parameters. However, it outperforms ones with trainable β_i when network depth is 20.

In the future, we will further investigate the link between neural network and dynamical system, try to give an explanation to this phenomenon.

Model	Layers	Error
Resnet	20	8.75
Resnet	32	7.51
Resnet	44	7.17
Resnet	56	6.97
LMResnet	20	8.33
LMResnet	32	7.18
LMResnet	44	6.66
LMResnet	56	6.31
Adamnet(k=2)(A)	20	8.15
Adamnet(k=2)(A)	32	7.31
Adamnet(k=2)(A)	44	6.75
Adamnet(k=2)(A)	56	6.44
Adamnet(k=2)(B)	20	7.81
Adamnet(k=2)(B)	32	7.49
Adamnet(k=2)(B)	44	6.90
Adamnet(k=2)(B)	56	6.71
Adamnet(k=3)(A)	20	8.27
Adamnet(k=3)(A)	32	7.39
Adamnet(k=3)(A)	44	7.02
Adamnet(k=3)(A)	56	6.36
Adamnet(k=3)(B)	20	8.02
Adamnet(k=3)(B)	32	7.54
Adamnet(k=3)(B)	44	7.14
Adamnet(k=3)(B)	56	6.97

Table 1: Results on CIFAR-10 dataset

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